

A Practical Construction for Decomposing Numerical Abstract Domains



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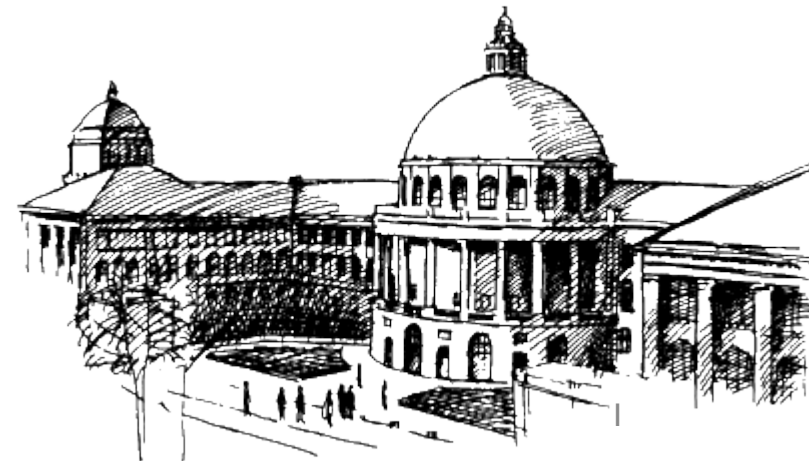
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Numerical abstract domains

Numerical Domain	Representable Constraints ($c \in \mathbb{Q}$ or \mathbb{R})	Cost and Expressivity
Interval	$\pm x_i \leq c$	
Pentagon	$(\pm x_i \leq c)$ or $(x_i \leq x_j)$	
Zones	$(\pm x_i \leq c)$ or $(x_i - x_j \leq c)$	
Octagon	$(\pm x_i \leq c)$ or $(\pm x_i \pm x_j \leq c)$	
TVPI	$a_i x_i + a_j x_j \leq c, a_i \in \mathbb{Z}$	
Polyhedra	$a_1 x_1 + a_2 x_2 + \dots + a_n x_n \leq c, a_i \in \mathbb{Z}$	

Static analysis with precise numerical domains is expensive

Domain transformers

Octagon

// abstract program state: $\{-x_1 - x_2 \leq 0, -x_2 \leq 0, -x_3 - x_4 \leq 0\}$

// program statement: **if** $(x_2 + x_3 + x_4 \leq 1)$

Best,
Exponential

$\{-x_1 - x_2 \leq 0, -x_2 \leq 0, -x_3 - x_4 \leq 0, x_2 \leq 1, x_3 + x_4 \leq 1, -x_1 \leq 1\}$

Standard,
Quadratic

$\{-x_1 - x_2 \leq 0, -x_2 \leq 0, -x_3 - x_4 \leq 0, x_3 + x_4 \leq 1\}$

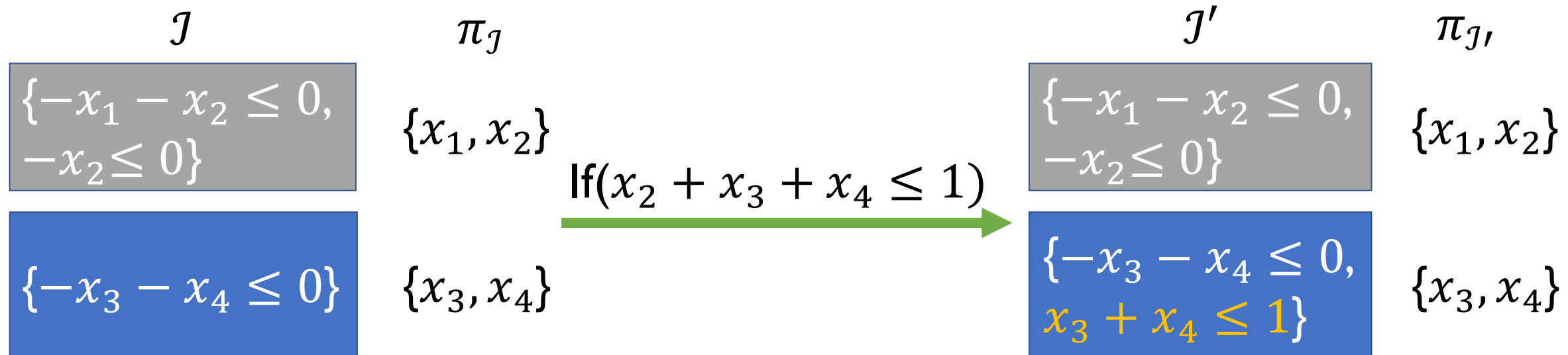
Trivial,
Constant

$\{\}$

Best abstract transformers for even less precise domains are expensive

Online decomposition

Numerical domain analysis can be made **faster** through online decomposition



- Decomposing standard Octagon analysis ([PLDI 2015])
- Decomposing standard Polyhedra analysis ([SAS 2003, POPL2017])

Limitations of prior work

- Numerical abstract domains and their transformers
 - ad hoc design
 - guided by cost precision tradeoff
 - tailored for specific use cases

Drawback: Prior work cannot be reused for new domain transformers

Required: Universal construction for decomposing numerical domains

Contributions

Original

Abstract
element +
Transformer
80 vars



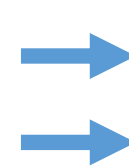
Black box
construction

Decomposed

32 vars
3 vars
28 vars
17 vars

Our decomposed analysis

- Significantly fast
- Always sound
- Monotonic
- Precise



Under practical
conditions

Complete end-to-end implementation

- Polyhedra
- Octagon
- Zones

Benchmark: >30K LOC, >550 vars

Analysis	Poly	Oct	Zones
Original	6142 s	28 s	3 s
Decomposed	4.4 s	1.9 s	1.5 s

Requirements on numerical abstract domains

- An abstract element \mathcal{J} in domain \mathcal{D} is conjunction of finite number of representable constraints
- The concretization function γ for \mathcal{D} should be meet preserving

$$\gamma(\mathcal{J} \sqcap \mathcal{J}') = \gamma(\mathcal{J}) \sqcap \gamma(\mathcal{J}')$$

- The ordering of abstract elements in the domain satisfies:

$$\mathcal{J} \sqsubseteq \mathcal{J}' \iff \gamma(\mathcal{J}) \subseteq \gamma(\mathcal{J}')$$

Partitioning variable set \mathcal{X}

Octagon

\mathcal{J}	Finest unique partition $\pi_{\mathcal{J}}$	\mathcal{J}	A permissible partition $\bar{\pi}_{\mathcal{J}}$	An invalid partition
$\{-x_1 - x_2 \leq 0\}$	$\{x_1, x_2\}$	$\{-x_1 - x_2 \leq 0\}$	$\{x_1, x_2\}$	$\{x_1, x_3\}$
$\{x_3 \leq 0\}$	$\{x_3\}$	$\{x_3 \leq 0, x_4 \leq 0\}$	$\{x_3, x_4\}$	$\{x_2\}$
$\{x_4 \leq 0\}$	$\{x_4\}$			$\{x_4\}$

- Expensive to maintain finest partitions thus online decomposition maintains permissible partitions

Decomposable transformers

Polyhedra

$$\{x_1 + x_2 \leq 0\}$$

$$\{x_1, x_2\}$$

//abstract program state:

$$\{x_3 + x_4 \leq 5\}$$

$$\{x_3, x_4\}$$

//program statement:

if ($x_5 + x_6 \leq 0$)

Non-decomposable

Decomposable

\mathcal{J}' $\{x_1 + x_2 + x_3 + x_4 + x_5 + x_6 \leq 5\}$

$$\bar{\pi}_{\mathcal{J}'} \{x_1, x_2, x_3, x_4, x_5, x_6\}$$

\mathcal{J}''

$\bar{\pi}_{\mathcal{J}''}$

$$\{x_1 + x_2 \leq 0\}$$

$$\{x_1, x_2\}$$

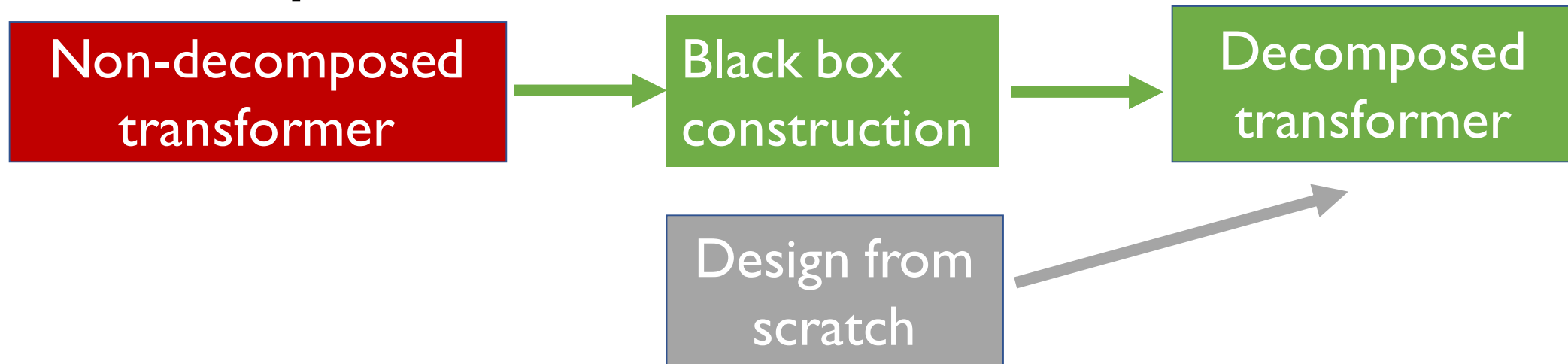
$$\{x_3 + x_4 \leq 5\}$$

$$\{x_3, x_4\}$$

$$\{x_5 + x_6 \leq 0\}$$

$$\{x_5, x_6\}$$

Decomposable transformers

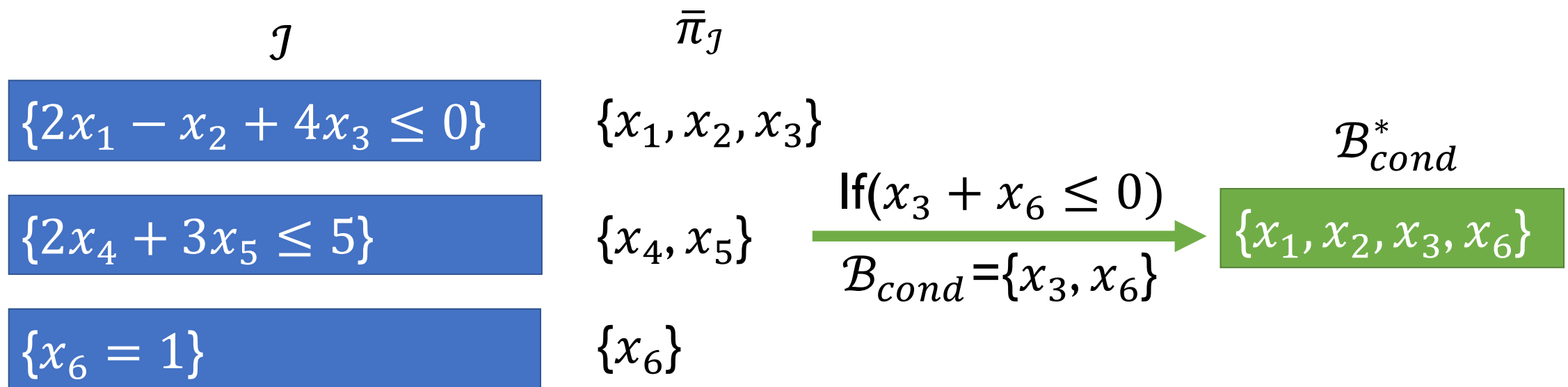


- Conditional
- Assignment
- Meet
- Join
- Widening

Conditional Transformer T_{cond}

Definition: Let \mathcal{J} be an abstract element in domain \mathcal{D} with the associated permissible partition $\bar{\pi}_{\mathcal{J}}$ and $\sum a_i x_i \leq c$ be the conditional statement then,

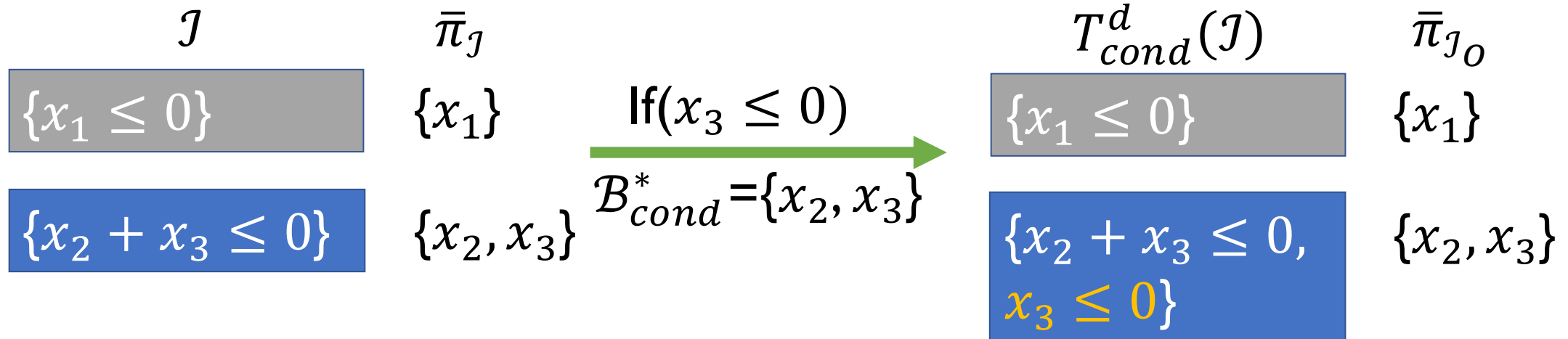
$$\mathcal{B}_{cond} := \{x_i : a_i \neq 0\}$$
$$\mathcal{B}_{cond}^* := \bigcup_{\mathcal{X}_k \cap \mathcal{B}_{cond} \neq \emptyset} \mathcal{X}_k, \mathcal{X}_k \in \bar{\pi}_{\mathcal{J}}$$



Conditional Transformer T_{cond}

$$\mathcal{J}_O := T_{cond}^d(\mathcal{J}) := T_{cond}(\mathcal{J}(\mathcal{B}_{cond}^*)) \cup \mathcal{J}(\mathcal{X} \setminus \mathcal{B}_{cond}^*)$$

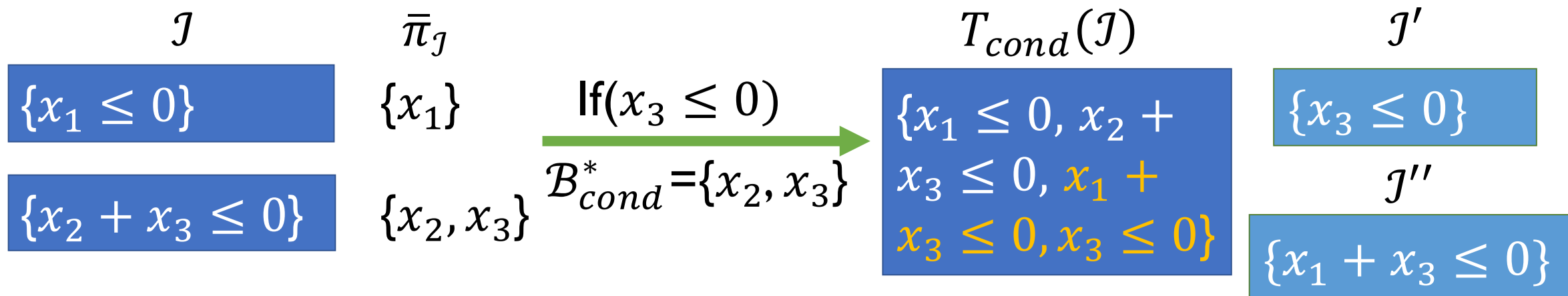
$$\bar{\pi}_{\mathcal{J}_O} := \{\mathcal{X}_k \in \bar{\pi}_{\mathcal{J}} : \mathcal{X}_k \cap \mathcal{B}_{cond}^* = \emptyset\} \cup \{\mathcal{B}_{cond}^*\}$$



Conditional Transformer T_{cond}

Theorem: $\gamma(T_{cond}(\mathcal{J})) = \gamma(T_{cond}^d(\mathcal{J}))$ if for any associated permissible partition $\bar{\pi}_{\mathcal{J}}$, the output $T_{cond}(\mathcal{J})$ satisfies:

- $T_{cond}(\mathcal{J}) = \mathcal{J} \cup \mathcal{J}' \cup \mathcal{J}''$ where \mathcal{J}' is a set of non-redundant constraints between the variables from \mathcal{B}_{cond}^* only and \mathcal{J}'' is a set of redundant constraints between the variables in \mathcal{X}
- $\gamma(T_{cond}(\mathcal{J}(\mathcal{B}_{cond}^*))) = \gamma(\mathcal{J}(\mathcal{B}_{cond}^*) \cup \mathcal{J}')$



$$\gamma(T_{cond}(\mathcal{J}(\mathcal{B}_{cond}^*))) = \gamma(\mathcal{J}(\mathcal{B}_{cond}^*) \cup \mathcal{J}') = \gamma(\{x_2 + x_3 \leq 0, x_3 \leq 0\})$$

Refinement

- The output partition can be refined after computing the output
 - non-invertible assignment
 - join
- Allows us to produce finer output partitions than prior work for
 - Polyhedra
 - Octagon

Experimental Evaluation

- Crab-llvm analyzer
 - intra procedural analysis
 - analyzes llvm bitcode
- Software verification competition benchmarks
 - linux device drivers
 - control flow
- Polyhedra
 - non decomposed transformers from PPL and decomposed from [POPL'17]
- Octagon
 - non decomposed and decomposed transformers from [PLDI'15]
- Zones
 - Implemented non decomposed transformers

Polyhedra

Benchmark	PPL (s)	POPL'17 (s)	POPL'18 (s)	Speedup vs	
				PPL	POPL'17
net_fddi_skfp	6142	9.2	4.4	1386	2
mtd_ubi	MO	4	1.9	∞	2.1
usb_core_main0	4003	65	29	136	2.2
tty_synclinkmp	MO	3.4	2.5	∞	1.4
scsi_advansys	TO	4	3.4	>4183	1.2
staging_vt6656	TO	2	0.5	>28800	4
net_ppp	10530	924	891	11.8	1
p10_100	121	11	5.4	22.4	2
p16_140	MO	11	2.9	∞	3.8
p12_157	MO	14	6.5	∞	2.1
p13_153	MO	54	25	∞	2.2
p19_159	MO	70	12	∞	5.9

Octagon

Benchmark	PLDI'15 ND(s)	PLDI'15 D(s)	POPL'18 (s)	Speedup vs	
				ND	D
net_fddi_skfp	28	2.6	1.9	15	1.4
mtd_ubi	3411	979	532	6.4	1.8
usb_core_main0	107	6.1	4.9	22	1.2
tty_synclinkmp	8.2	1	0.8	10	1.2
scsi_advansys	9.3	1.5	0.8	12	1.9
staging_vt6656	4.8	0.3	0.2	24	1.5
net_ppp	11	1.1	1.2	9.2	0.9
p10_100	20	0.5	0.5	40	1
p16_140	8.8	0.6	0.5	18	1.2
p12_157	19	1.2	0.7	27	1.7
p13_153	43	1.7	1.3	33	1.3
p19_159	41	2.8	1.2	31	2.2

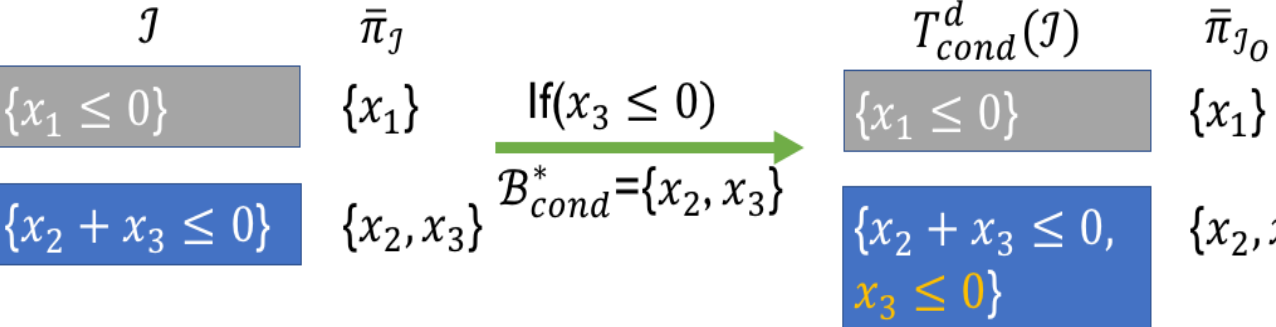
Zones

Benchmark	Non Decomposed (s)	POPL'18 (s)	Speedup
net_fddi_skfp	3	1.5	2
mtd_ubi	1.4	0.7	2
usb_core_main0	10.3	4.6	2.2
tty_synclinkmp	1.1	0.7	1.6
scsi_advansys	0.9	0.7	1.3
staging_vt6656	0.5	0.2	2.5
net_ppp	1.1	0.7	1.5
p10_100	1.9	0.4	4.6
p16_140	1.7	0.7	2.5
p12_157	3.5	0.9	3.9
p13_153	8.7	2.1	4.2
p19_159	9.8	1.6	6.1

Black box construction

$$J_0 := T_{cond}^d(J) := T_{cond}(J(\mathcal{B}_{cond}^*)) \cup J(\mathcal{X} \setminus \mathcal{B}_{cond}^*)$$

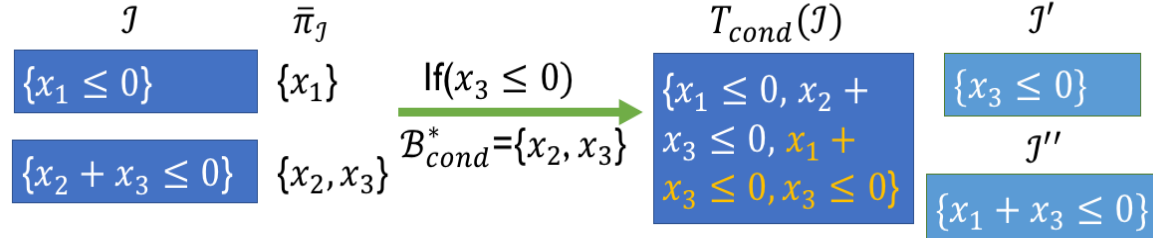
$$\bar{\pi}_{J_0} := \{\mathcal{X}_k \in \bar{\pi}_J : \mathcal{X}_k \cap \mathcal{B}_{cond}^* = \emptyset\} \cup \{\mathcal{B}_{cond}^*\}$$



Same precision in practice

Theorem: $\gamma(T_{cond}(J)) = \gamma(T_{cond}^d(J))$ if for any associated permissible partition $\bar{\pi}_J$, the output $T_{cond}(J)$ satisfies:

- $T_{cond}(J) = J \cup J' \cup J''$ where J' is a set of non-redundant constraints between the variables from \mathcal{B}_{cond}^* only and J'' is a set of redundant constraints between the variables in \mathcal{X}
- $\gamma(T_{cond}(J(\mathcal{B}_{cond}^*))) = \gamma(J(\mathcal{B}_{cond}^*) \cup J')$



$$\gamma(T_{cond}(J(\mathcal{B}_{cond}^*))) = \gamma(J(\mathcal{B}_{cond}^*) \cup J') = \gamma(\{x_2 + x_3 \leq 0, x_3 \leq 0\})$$

Complete end-to-end implementation

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Benchmark: >30K LOC, >550 vars

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